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Detection of interacting variables for generalized linear models using neural networks

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Presentation overview

Motivation and context

Reminder of a Poisson GLM

Existing approaches and our proposal

Case studies

Summary and conclusions

Motivation and context

- Actuaries have huge data sets, especially in motor third party liability (MTPL) insurance
- Insurers use generalized linear models (GLMs) due to interpretability of these models and companies' IT legacy
- GLMs are improved by actuaries via sophisticated choice of significant variables and their interactions
- Search for strong interactions is more time-consuming, is mostly visual and depends much on expert judgement
- Example: for 20 variables \approx 200 pairwise interactions, for 50 variables \approx 1200 pairwise interactions
- A recommendation engine for the next-best interaction missing in a GLM may save actuaries hours/days
- Why next-best? GLMs for tariffs cannot be drastically changed/replaced but should be adjusted gradually
- For automatic tree-based construction of a GLM from scratch, see, e.g., Henckaerts et al. (2022)



Problem setting and business requirements

- Given:
 - the predictions of a benchmark GLM (e.g., claim counts)
 - training data (e.g., driver's age, profession, car brand, postcode)
- Find:
 - Next-best pairwise interaction missing in the benchmark GLM (e.g., interaction between postcode and bonus malus)
- Subject to business requirements:
 - 1 Avoid retraining the benchmark GLM, use only its predictions
 - 2 "Next-best" means in terms of key performance indicators (KPIs) that actuaries rely on, e.g., lift plots
 - 3 Minimize the need for visual evaluation of KPIs



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Notation

- $\mathcal{D} = \{(N_i, \boldsymbol{x}_i, v_i)\}_{i=1}^n$ data set, where
 - $n \in \mathbb{N}$ is the number of observations
 - $-v_i \in [0, 1]$ corresponds to the exposure time in years for the *i*-th observation
 - $N_i \in \mathbb{N} \cup \{0\}$ is the number of claims observed for the *i*-th observation within exposure time v_i
 - $\mathbf{x}_i \in \mathcal{X} \subset \{1\} \times \mathbb{R}^p$ represents the vector of covariates for the *i*-th observation excluding v_i
 - $\ p \in \mathbb{N}$ is the number of covariates
- $x_{.,j}$ denotes covariate $j = 1, \ldots, p$

Poisson GLM

• Poisson GLM with the canonical link assumes

 $N_i \sim \text{Poisson}(v_i \exp(\eta(\boldsymbol{\beta}, \boldsymbol{x}_i))),$

where $\eta(\boldsymbol{\beta}, \boldsymbol{x}_i) = \boldsymbol{\beta}^T \boldsymbol{x}_i$ – the linear component and β is the vector of the GLM parameters

- Denote by $\hat{\lambda}_i^{GLM} := \exp(\eta(\hat{\beta}, \mathbf{x}_i))$ the annualized claim frequency predicted by a GLM
- An interaction is a term $I(x_{i,1}, x_{i,2})$ added to the component $\eta(\beta, \mathbf{x}_i)$ such that $I(x_{i,1}, x_{i,2})$ is not additively separable, e.g.:
 - for numerical $x_{.,1}$, $x_{.,2}$ we can have:

$$I(x_{i,1}, x_{i,2}) = \beta_{1,2} \cdot x_{i,1} \cdot x_{i,2}$$

− for numerical $x_{.,1}$ and categorical $x_{.,2}$ with $J \in \mathbb{N}$ categories and J as a reference category:

$$I(x_{i,1}, x_{i,2}) = \sum_{j=1}^{J-1} \beta_j \cdot x_{i,1} \cdot \mathbb{1}_{\{x_{i,2}=j\}}$$

− for categorical $x_{.,1}$ with $J \in \mathbb{N}$ categories and categorical $x_{.,2}$ with $K \in \mathbb{N}$ categories:

$$I(x_{i,1}, x_{i,2}) = \sum_{j=1}^{J-1} \sum_{k=1}^{K-1} \beta_{j,k} \cdot \mathbb{1}_{\{x_{i,1}=j\}} \cdot \mathbb{1}_{\{x_{i,2}=k\}}$$



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Popular existing approaches and our contribution

- Approach known from practitioners:
 - train a Gradient Boosting Machine (GBM) with trees of depth 2 and benchmark GLM predictions as offset
 - compute Friedman's H-statistic (Friedman and Popescu (2008)) for each pair of features



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 - train a Gradient Boosting Machine (GBM) with trees of depth 2 and benchmark GLM predictions as offset
 - compute Friedman's H-statistic (Friedman and Popescu (2008)) for each pair of features
- Approach in Wüthrich (2020):
 - train a Combined Actuarial Neural Network (CANN) for each pair of features
 - for each CANN, compute the decrease of loss function in comparison to benchmark GLM



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- Approach in Wüthrich (2020):
 - train a Combined Actuarial Neural Network (CANN) for each pair of features
 - for each CANN, compute the decrease of loss function in comparison to benchmark GLM
- Our contribution:
 - 1 our approach is computationally faster, especially for data sets with many variables
 - 2 we address the question of automating the "best" functional form of the interaction





Overview of our approach

- Algorithm:
 - 1 Train Combined Actuarial Neural Network (CANN) using all variables
 - 2 Calculate strength of all pairwise interactions via Neural Interaction Detection (NID), sort from strongest to weakest
 - 3 Train mini-GLMs for top ranked interaction(s), identify the best mini-GLM, recommend the corresponding interaction





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- Motivation for each component:
 - 1 CANN captures well non-linear interactions missing in an actuarial model and allows for embedding layers
 - 2 NID is fast, does not rely on partial dependence plots or data reshuffling, easy to implement
 - 3 mini-GLMs help identify next-best interaction among top-ranked interations and its "optimal" functional form

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Algorithm Step 1: CANN

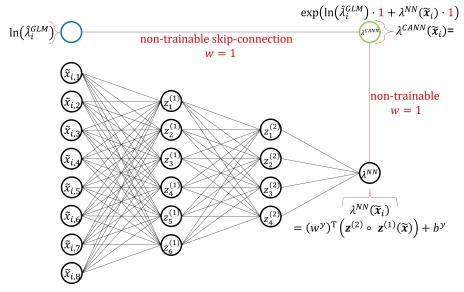


Figure: Figure taken from Havrylenko and Heger (2023)

- CANN was proposed in Wüthrich and Merz (2019)
- Two parts: GLM (non-trainable), NN (trainable)
- $W^{(l)}$ weight matrix, $\boldsymbol{b}^{(l)}$ bias vector for hidden layer l = 1, ..., d, where $d \in \mathbb{N}$ is number of hidden layers

•
$$\boldsymbol{w}^{\boldsymbol{y}}$$
 coefficient vector, $\boldsymbol{b}^{\boldsymbol{y}}$ bias for output neuron

•
$$\phi_l(\cdot)$$
 activation function of neurons in layer *I*, $\phi_{d+1}(z) = z$

• Vector of activation values in hidden layers (HLs):

$$oldsymbol{z}^{(l)}=\overrightarrow{\phi_l}\left(oldsymbol{W}^{(l)}oldsymbol{z}^{(l-1)}+oldsymbol{b}^{(l)}
ight)$$
, $I=1,\ldots,d$,

 $q_l \in \mathbb{N}, \, oldsymbol{z}^{(0)} := oldsymbol{ ilde{x}}$ input features

- Assumptions of a Poisson CANN:
 - $N_i \sim \mathsf{Poisson}(v_i \cdot \lambda^{\mathsf{CANN}}(\tilde{\boldsymbol{x}}_i))$

 $(- \boldsymbol{w}^{y} = (0, 0, \dots, 0)^{ op} \in \mathbb{R}^{q_{d}}, \, b^{y} = 0 \text{ at initialization}$

Algorithm Step 2: NID

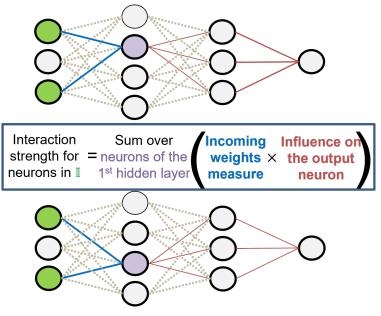


Figure: Figure taken from Havrylenko and Heger (2023)

• NID proposed in Tsang et al. (2018) for NN and num. ftrs.

- We modify NID to CANN and categorical variables
- Assumption: interactions are captured in the 1-st HL
- Interaction strength between input neurons in I measured at *j*-th neuron in 1-st HL:

$$s_j(\mathbb{I}) = \min(|W_{j,\mathbb{I}}^{(1)}|) \cdot \zeta_j^{(1)}, \ s_j(\mathbb{I}) \in \mathbb{R}$$

- |W⁽¹⁾_{j,I}| absolute value of incoming weights from input neurons in I to *j*-th neuron in 1-st HL
- Influence of *j*-th neuron in 1-st HL is *j*-th element of

$$\boldsymbol{\zeta}^{(1)} = |\boldsymbol{w}^{\boldsymbol{y}}|^\top \cdot |\boldsymbol{W}^{(d)}| \cdot |\boldsymbol{W}^{(d-1)}| \cdot ... \cdot |\boldsymbol{W}^{(2)}|, \ \boldsymbol{\zeta}^{(1)} \in \mathbb{R}^{q_1}$$

 $\bullet\,$ Total interaction strength score for input neurons in $\mathbb I$

$$s(\mathbb{I}) = \sum_{j=1}^{q_1} s_j(\mathbb{I}) = \sum_{j=1}^{q_1} \min(|W_{j,\mathbb{I}}^{(1)}|) \cdot \zeta_j^{(1)}$$
NNs



Algorithm Step 3: mini-GLMs and recommendation

- One cannot blindly recommend the interaction first-ranked by NID:
 - 1 a categorical variable in the interaction may require clustering of its categories (e.g., postcode, car brand)
 - 2 another top-ranked interaction may have a very similar NID score
 - 3 the functional form of the interaction for a GLM is not known in general
- Point 1: Cluster num. representations of cat. variables that appear in top-ranked interaction(s) and have many categories
- Points 2 and 3 are dealt as follows:
 - 1 Fit "mini-GLMs" for top-ranked pair(s) of interacting variables with different $I(x_{.,j}, x_{.,k})$, bench. GLM prediction is an offset:

$$N_i \sim ext{Poisson}\left(v_i \cdot \hat{\lambda}_i^{GLM} \cdot \exp(I(x_{i,j}, x_{i,k}))
ight)$$

2 Recommend the interaction that corresponds to mini-GLM with the best performance on relevant KPIs



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Case study 1: artificial data and algorithm step 1

• Artificially generated \mathcal{D} with $(x_{i,1}, \ldots, x_{i,8}) \sim N(0, \Sigma)$, where Σ is identity matrix except $\Sigma_{2,8} = \Sigma_{8,2} = 0.5$, $x_{i,9} \sim Binomial(2, 0.3), x_{i,10} \sim Binomial(5, 0.2), v_i = 1$:

$$\begin{split} \boldsymbol{x}_{i} \in \mathbb{R}^{10} \mapsto \eta(\boldsymbol{x}_{i}) &= -3 + 0.5 \cdot x_{i,1} - 0.25 \cdot x_{i,2}^{2} + 0.5 \cdot |x_{i,3}| \cdot \sin(2 \cdot x_{i,3}) + 0.5 \cdot x_{i,4} \cdot x_{i,5} \\ &+ 0.125 \cdot x_{i,5}^{2} \cdot x_{i,6} - 0.1 \cdot \mathbf{1}_{\{x_{i,9}=1\}} - 0.2 \cdot \mathbf{1}_{\{x_{i,9}=2\}} + 0.1 \cdot \mathbf{1}_{\{x_{i,10}=1\}} \\ &+ 0.2 \cdot \mathbf{1}_{\{x_{i,10}=2\}} + 0.3 \cdot \mathbf{1}_{\{x_{i,10}=3\}} + 0.4 \cdot \mathbf{1}_{\{x_{i,10}=4\}} + 0.5 \cdot \mathbf{1}_{\{x_{i,10}=5\}} \cdot \\ &N_{i} \sim \text{Poisson}(\exp(\eta(\boldsymbol{x}_{i}))), \quad i = 1, \dots, 2 \cdot 10^{6} \end{split}$$

- $\eta(\mathbf{x}_i)$ is taken from Richman and Wüthrich (2023) and modified such that the portfolio distribution looks realistic
- $\lambda^{GLM}(\mathbf{x}_i)$ with all main effects, but no interactions
- In step 1, a CANN with 3 HLs is trained using:
 - pre-processed variables (min-max scaling for numerical, one-hot encoding for $x_{.,9}$ and 2-dim. embedding for $x_{.,10}$)
 - fine-tuning of activation functions and the number of neurons in each HL



Case study 1: algorithm step 2

Interaction rank	Feature 1 name	Feature 2 name	Interaction strength score	
1	x .,4	x .,5	70.0263	CANN + NID results computation time: 170 sec. for CANN + 1.2 sec. for NID
2	x .,5	x .,6	37.3492	
3	x .,4	x .,6	34.7608	
4	$x_{\cdot,5}$	$x_{\cdot,10}$	24.3280	
5	x .,4	$x_{\cdot,10}$	23.9654	

Interaction rank	Feature 1 name	Feature 2 name	Interaction strength score	
1	x .,4	x .,5	0.8495	GBM + H-statistic results
2	x .,5	<i>x</i> .,6	0.2223	computation time: 120 sec. for GBM + 40 sec. for H-statistic on 0.5% of data (350 sec. for H-statistic on 5% of data)
3	x .,3	$x_{\cdot,5}$	0.0156	
4	x .,3	$x_{\cdot,6}$	0.0055	
5	x .,3	$x_{\cdot,4}$	0.0001	

(j)



Case study 1: algorithm step 3

- Since the functional form of $I(x_{.,4}, x_{.,5})$ is not known for non-categorical variables, one can:
 - categorize $x_{.,4} \to x_{.,4}^c$ as well as $x_{.,5} \to x_{.,5}^c$ and recommend $I(x_{.,4}^c, x_{.,5}^c) = \sum_{j=1}^{J-1} \sum_{k=1}^{K-1} \beta_{j,k} \cdot \mathbb{1}_{\{x_{i,4}^c = j\}} \cdot \mathbb{1}_{\{x_{i,5}^c = k\}}$ or
 - train mini-GLMs with various "reasonable" $I(x_{.,4}, x_{.,5})$ (from a selection of elementary functions or inferred from data visualization) and identify the best-performing one
- In our example, mini-GLM with $I(x_{.,4}, x_{.,5}) = \beta_{4,5} \cdot x_{.,5} \cdot x_{.,5}$ has the best KPIs, so this $I(\cdot, \cdot)$ is recommended for bench. GLM
- When $I(x_{.,4}, x_{.,5}) = \beta_{4,5} \cdot x_{.,4} \cdot x_{.,5}$ is added to the benchmark GLM, out-of-sample Poisson deviance \downarrow from 0.3314 to 0.3134
- Repeating steps 1 & 2 for updated GLM ranks $(x_{.,5}, x_{.,6})$ as (by far) 1-st ranked
- In step 3, mini-GLMs with $I(x_{.,5}, x_{.,6}) = \beta_{5,6} \cdot x_{.,5}^a \cdot x_{.,6}^b$ for $a \in \{1, 2, 3\}$ and $b \in \{1, 2, 3\}$ are trained and KPIs are evaluated
- $I(x_{.,5}, x_{.,6}) = \beta_{5,6} \cdot x_{.,6}^2 \cdot x_{.,6}$ is recommended for the benchmark GLM





Case studies with open-source data and big proprietary data

- *freMTPL2freq* data set with \approx 680000 observations, 9 variables, so 36 potential pairwise interactions:
 - Alg. step 1 takes 90 sec. for 1 CANN (comparable for 1 GBM)
 - Alg. step 2 takes < 1 sec., whereas the computation of Friedman's H-statistics takes 5 minutes
 - Alg. step 3 recommends *I*(*VehAge*, *BonusMalus*) or *I*(*VehAge*, *VehGas*), depending on KPI for mini-GLM
 - Both interactions are among top ones as per GBM + Friedman's H-statistic
 - Schelldorfer and Wüthrich (2019) does not have *I*(*VehAge*, *VehGas*) in the list of detected interactions



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 - Schelldorfer and Wüthrich (2019) does not have *I*(*VehAge*, *VehGas*) in the list of detected interactions
- Confidential data with \approx 11 mln. observations, \approx 50 variables, so \approx 1225 potential pairwise interactions:
 - Alg. step 2 takes < 3 sec., whereas calculating Friedman's H-statistics is too costly even for 5% of data
 - Dimensionality reduction of large cat. variables like *postcode* or *carBrand* is also beneficial for actuaries



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Summary and conclusions

- Detection of interactions missing in GLMs can be very time-consuming
- We contribute to the academic literature on the detection of interacting variables for GLMs by
 - proposing an interaction-detection methodology that is signif. faster than alernatives and has a comparable quality
 - pioneering the usage of NID in actuarial science
 - modifying NID to CANNs and categorical variables
- Advantages of proposed methodology:
 - almost fully automatable with little to no need for actuarial intervention
 - faster than other approaches \Rightarrow especially suitable for big data
 - represents large categorical variables as low-dimensional num. vectors
- Research outlook: analyze robustness of the algorithm, improve automation of Step 3 Yevhen Havrylenko (yh@math.ku.dk) | Detection of interacting variables for GLMs using NNs

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I thank you for your attention...

... and look forward to your questions!





(a) QR code to Havrylenko and Heger (2023)

(b) QR code to https://war.ukraine.ua/support-ukraine/

NID vs Friedman's H-statistic

NID

- <u>Model-specific</u>, only applicable for feed-forward NNs
- <u>Based on the learned weights incoming in 1st hidden</u>
 layer of NN and outgoing paths to the output neuron
- <u>Assumes that the interactions</u> are learned by the neural network and <u>happen in the first hidden layer</u>
- Does not allow for comparison across different NNs
- Always leads to the same result for a fixed NN
- Computationally fast

Friedman's H-statistic

- Model-agnostic, i.e., applicable to any model
- <u>Based on partial dependence decomposition</u> and calculates share of variance explained by interaction
- <u>Assumes that features can be shuffled</u>, which is violated if features are strongly correlated
- <u>Allows for comparison across different models</u>
- May lead to unstable results depend. on used data
- <u>Computationally time-consuming</u>

Both methods

- Can detect interactions of order higher than 2 (more computationally demanding)
- Can detect various forms of interactions, independently of their specific structure
- Do not provide the functional form of the interaction
- Do not clearly indicate whether the interaction is statistically significant