

Disability insurance with information delays

Oliver Lunding Sandqvist

Industrial PhD student

University of Copenhagen and PFA Pension

CONVENTION A

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Overview

- 1 Introduction
- 2 Available data
- 3 Reserving
- 4 Estimation
- 5 Data application
- 6 Closing remarks

Background

Talk is based on three papers (available on ArXiv):

- **Transaction time models in multi-state life insurance**
 - Jointly with Kristian Buchardt and Christian Furrer.
 - Published in SAJ 01/03/2023.
- **Estimation for multistate models subject to reporting delays and incomplete event adjudication**
 - Jointly with Kristian Buchardt and Christian Furrer.
- **A multistate approach to disability insurance reserving with information delays**

Background

Why disability insurance?

Competitive market

Long cash flows

Rapid changes/trends

Discrepancy between theory and practice

Classic semi-Markov disability model

- Semi-Markov model $\{Y(t)\}_{t \geq 0}$ for insurance events.
- State space:

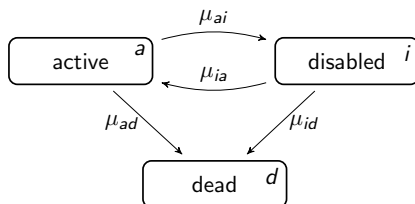


Figure 1: Illness-death model.

- Baseline covariates (age, gender, etc.) suppressed throughout, but could easily be included by conditioning on them.
- References: Janssen (1966), Hoem (1972), Haberman and Pitacco (1998), Helwich (2008), Christiansen (2012), and Buchardt et al. (2015).

Classic semi-Markov disability model

- Cash flow (specified in the insurance contract):

$$B(dt) = \sum_j 1_{(Y(t-)=j)} b_j(t, U(t-)) dt + \sum_{j \neq k} b_{jk}(t, U(t-)) N_{jk}(dt).$$

- Counting processes $N_{jk}(t) = \# \text{jumps from } j \text{ to } k \text{ before time } t$.
- Duration process $U(t) = \text{duration since last jump at time } t$.
- Interest rate: $r(t)$.
- Present value: $PV(t) = \int_t^\infty e^{-\int_t^s r(v) dv} dB(s)$.
- Prospective reserve:

$$V(t) = V_{Y(t)}(t, U(t)) = \mathbb{E} \left[PV(t) \mid Y(t), U(t) \right].$$

Classic semi-Markov disability model

- Maximum likelihood estimation (MLE) based on $[0, t]$ observations discretized in $0 = t_0 < t_1 < \dots < t_M = t$:
 - Occurrences and exposures:

$$O_{jk}(t_m) = N_{jk}(t_{m+1}) - N_{jk}(t_m),$$
$$E_j(t_m) = \int_{t_m}^{t_{m+1}} 1\{Y(s-) = j\} ds.$$

- Input $(O_{jk}(t_m))_{j,k,m}$ into `glm` as independent observations where $O_{jk}(t_m)$ has mean $\mu_{jk}(t_m, U(t_m), \beta)E_j(t_m)$ for regressor β .
- References: Lindsey (1995).

Research problems

Problem: Y not fully observed due to reporting and processing delays.

- Reserving: Can't compute $V(t)$ if $(Y(t), U(t))$ not fully known at time t and can't assume $B(t)$ is paid at time t .
- Estimation: Can't estimate using likelihood since occurrences and exposures not fully known at time t .

Content of presentation:

- Describe available data.
- Reserving proposal.
- Estimation proposal.
- Data application.

Available information

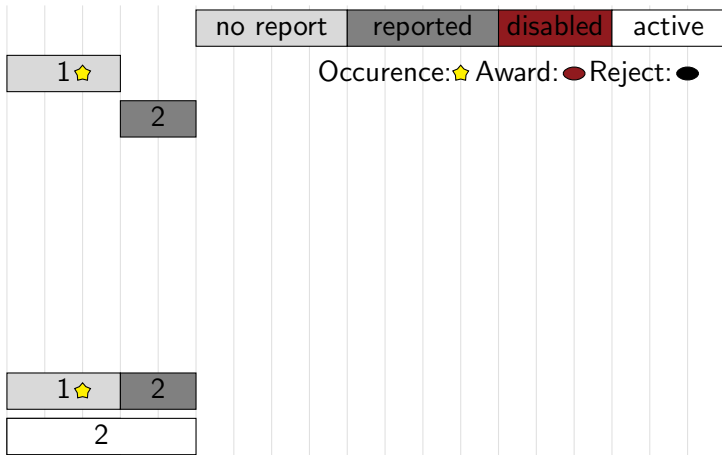
Example: Available information for one insured.

no report reported disabled active

Occurence: ☆ Award: ● Reject: ●

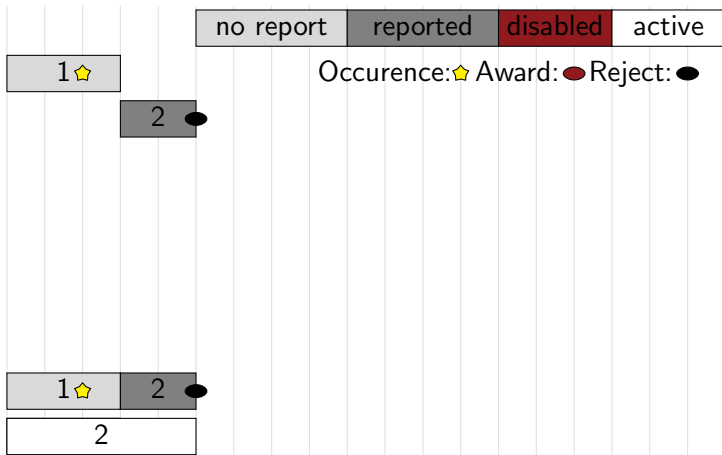
Available information

Example: Available information for one insured.



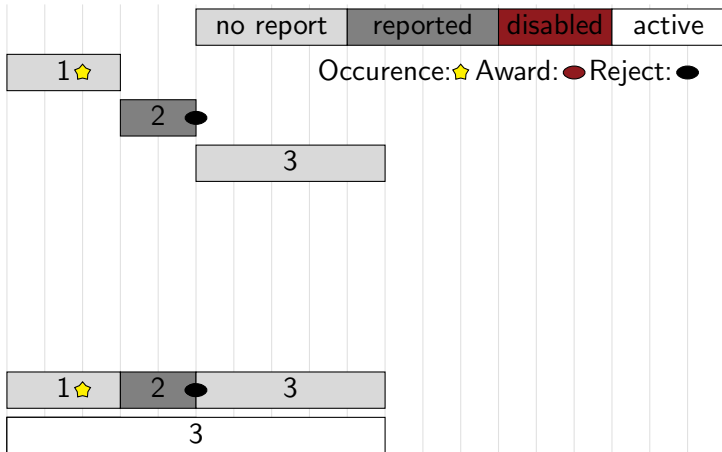
Available information

Example: Available information for one insured.



Available information

Example: Available information for one insured.



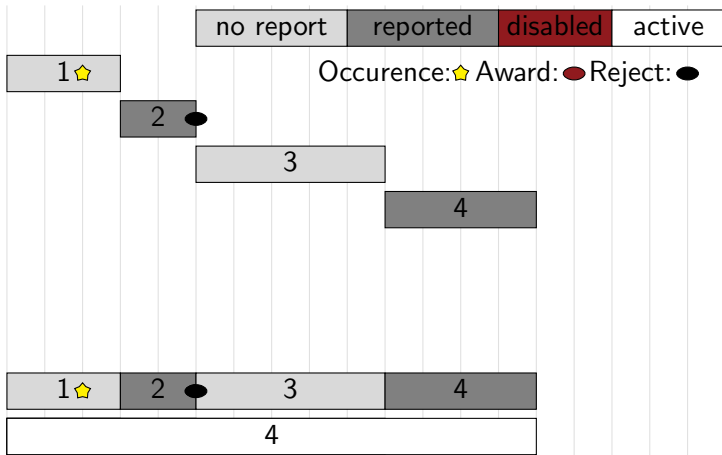
Events:

Observed

Insurance

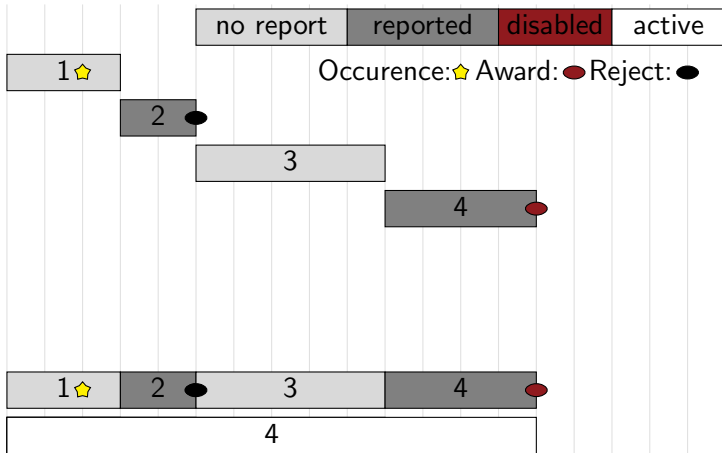
Available information

Example: Available information for one insured.



Available information

Example: Available information for one insured.



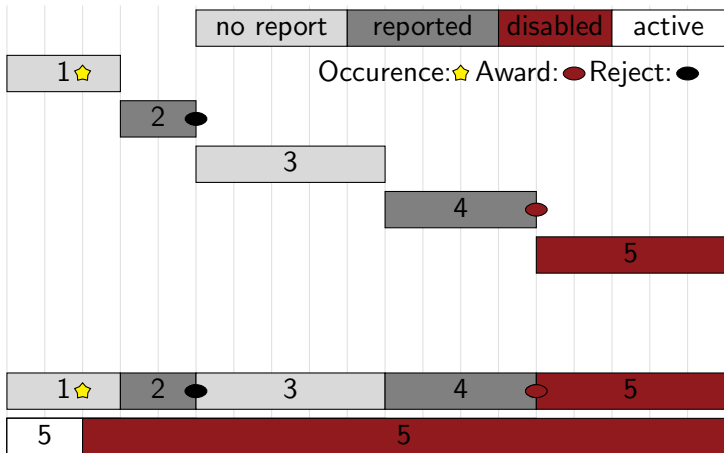
Events:

Observed

Insurance

Available information

Example: Available information for one insured.



Disability insurance features

- Reasons for substantial reporting delays?
- Reasons for substantial adjudication processes?
- Disability insurance features:
 - Long cash flows \sim life insurance.
 - Long reporting and adjudication delays \sim non-life insurance.
- Modeling goal: Retain attractive properties of multistate models while accommodating reporting delays and adjudication processes.

Proposed disability model

- Jump process model $\{Z(t)\}_{t \geq 0}$ for claim settlement process.
- State space:

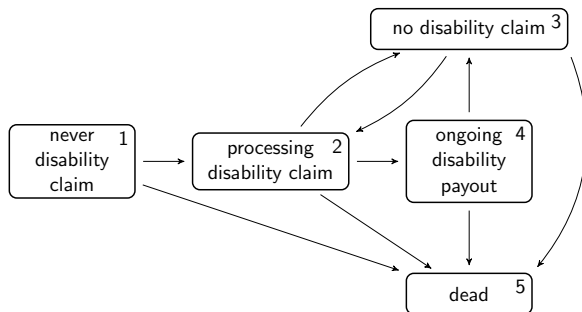


Figure 2: Claim settlement state space.

- Additional observed information:
 - The reported disability event time upon a transition into state 2.
 - What is awarded upon a transition out of state 2.

Proposed disability model

- Claim settlement reserve: $\mathcal{V}(t)$.
- Reserve $\mathcal{V}(t)$ differs from $V(t)$ in two ways:
 - ➊ Reserve additionally to backpay (*= lump sum due to delay in payout of benefits that the insured was eligible for*).
 - ➋ Reserve is a function of Z instead of (Y, U) .

Proposed disability model

Proposed state-wise claim settlement reserves (simplified):

- State 1 (never disability claim):

$$\mathcal{V}(t) = V_a(t) + \int_0^t V_i(s, 0) I(t-s) \mu_{ai}(s) ds.$$

- $I(t-s) = \mathbb{P}(\text{Disability reporting delay} > t-s).$
- State 2 & 3 (processing disability claim & no disability claim):

$$\mathcal{V}(t) = p(t) V_i(G(t), W(t)).$$

- $p(t) = \mathbb{P}(\text{Award after time } t).$
- $G(t) = \text{Start of next disability period if awarded after time } t.$
- $W(t) = \text{Length of awarded disability period by time } t.$

Proposed disability model

Proposed state-wise claim settlement reserves (simplified):

- State 4 (ongoing disability payout): $\mathcal{V}(t) = V_i(t, W(t))$.
- State 5 (dead): $\mathcal{V}(t) = V_d(t)$.

Estimation

- What to estimate:
 - Classic transition hazards: $(s, u) \mapsto \mu_{jk}(s, u)$.
 - Reporting delay distribution: $s \mapsto l(s)$.
 - Award probabilities: $s \mapsto p(s)$.
- $p(s)$ can be modeled as probability of hitting state 3 in Figure 3:

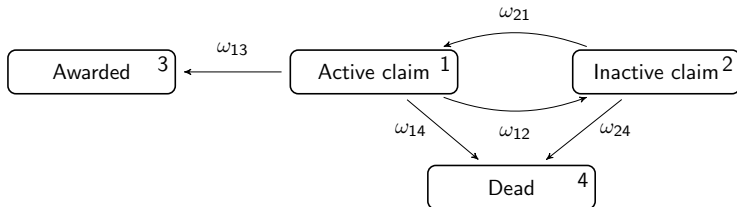


Figure 3: State space for adjudication.

Estimation procedure

Estimation procedure with time of analysis t :

- ① $p(s)$: MLE for ω_{jk} and plug in.
- ② $l(s)$: MLE for the reporting delays conditional on the delay being less than $t - T_{\text{disability}}$ and weighted with $p(t)$.
- ③ $\mu_{jk}(s, u)$: MLE based on the observed occurrences $O_{jk}^{\text{obs}}(t_m)$ and exposures $E_j^{\text{obs}}(t_m)$ after modifying as follows:

$$O_{ai}^{\text{obs}}(t_m) \leftarrow O_{ai}^{\text{obs}}(t_m)p(t),$$

$$O_{ia}^{\text{obs}}(t_m) \leftarrow O_{ia}^{\text{obs}}(t_m)(1 - p(t)),$$

$$E_a^{\text{obs}}(t_m) \leftarrow E_a^{\text{obs}}(t_m)(1 - l(t - t_m)).$$

Estimator properties

- Consistency and joint asymptotic normality follows by two-step M-estimation results.
- References: Newey and McFadden (1994).

Application to real data

- Anonymized and slightly altered real disability insurance data.
 - Disability exposure and occurrences.
 - Reactivation exposure and occurrences.
 - Disability reporting delays.
 - Adjudication exposure and occurrences.
- Time window $[0, t]$ is $[31/01/2015, 01/09/2019]$.
- Available on <https://github.com/oliversandqvist/Web-appendix-estimation-contamination>.

Application: Estimation

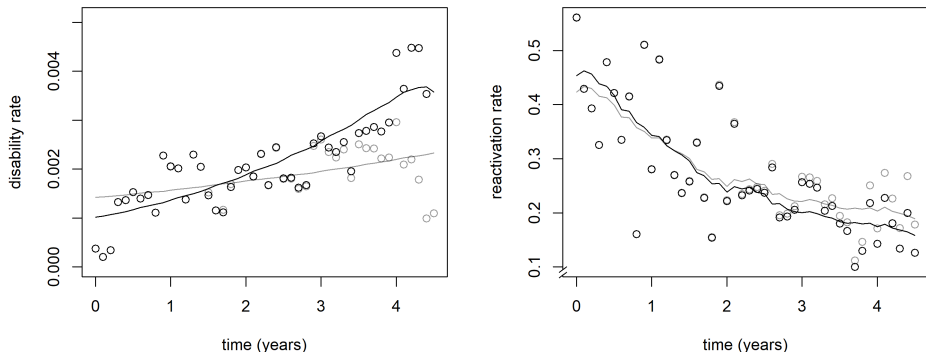


Figure 4: Fitted rates (lines) and occurrence-exposure rates (points) for the proposed method (black) and the naive method (gray). Disability rates are shown on the left and reactivation rates on the right.

Application: Reserving

Assume disability rate with 3 year coverage period

$$B(dt) = 1\{Y(t-) = i\}1\{t - U(t-) \leq 3\}1\{\text{Age}_0 + t \leq 67\} dt.$$

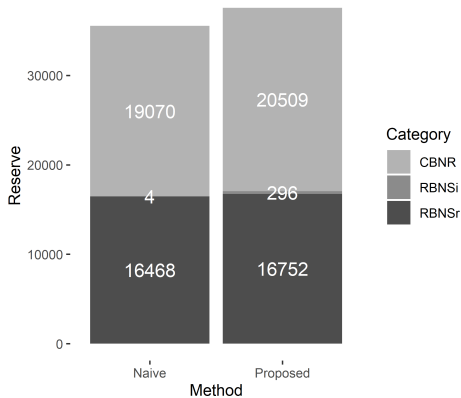


Figure 5: Portfolio level reserve decomposed by category.

Application: Reserving

- Proposed method leads to 5.7% increase in reserves compared to naive approach.
- Two large Danish insurers in 2019: Portfolio disability reserves of 1.4 billion USD and 2.6 billion USD.
- A 5.7% increase in these reserves is 80 million USD and 150 million USD respectively.

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Thank you for your attention!